

Science-informed Machine Learning for Accelerating Real-Time Decisions in Subsurface Applications

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Problems and motivations

- Bring AI and machine learning (ML) capabilities to
 - Inform pre-injection permitting
 - Class VI permit (characterization, uncertain quantification, plume assessment)
 - Site development
 - History matching
 - Operation optimization
 - Induced seismicity
- Visualization (real-time)
- Idea is to use AI and ML to speed up these simulations by orders of magnitude

Carbon Storage

Technical Team



Oil & Gas

Technical Team

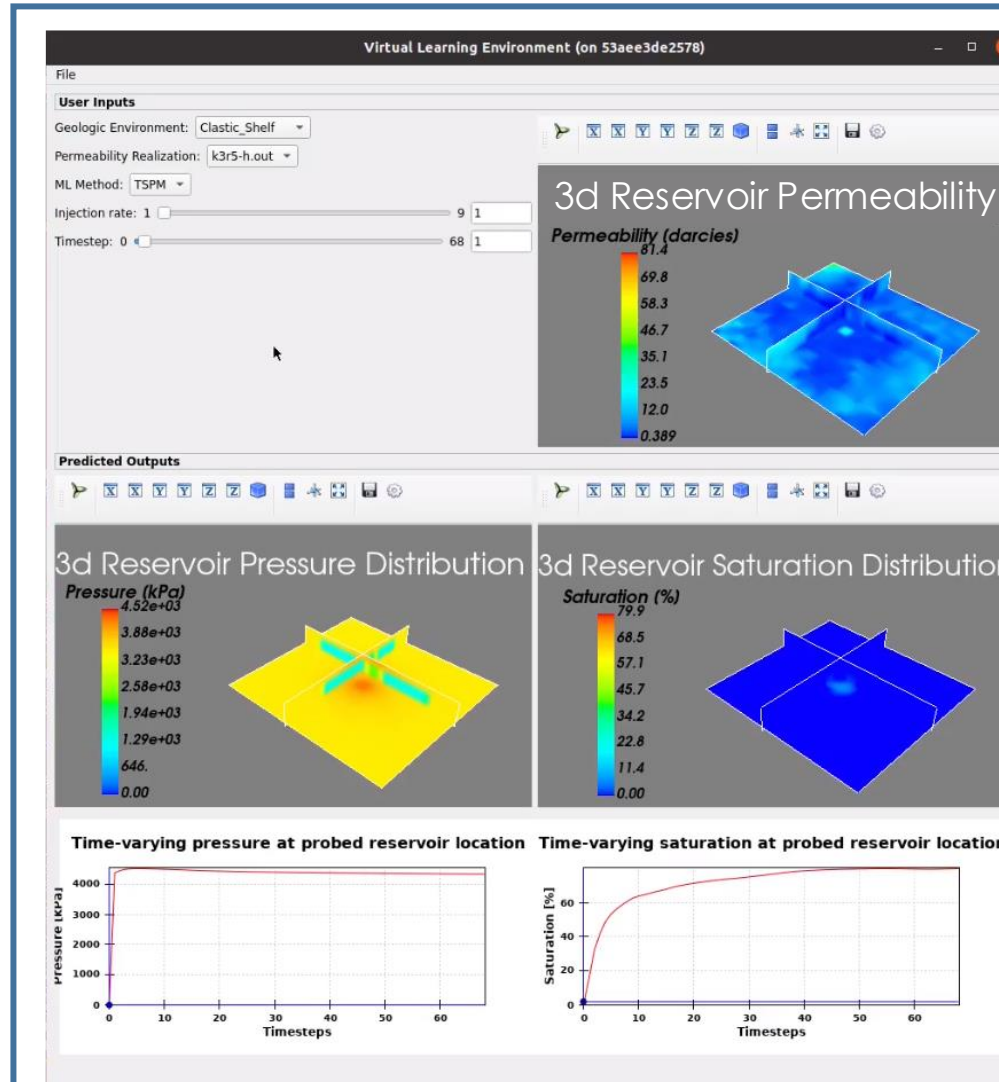


Task 5 Motivation

Can we rapidly develop experience among CCS stakeholders to facilitate rapid & safe deployment of large-scale geologic CO₂ storage?

Vision: Enable a Virtual Learning Environment (VLE) for exploring and testing strategies to optimize reservoir development, management & monitoring prior to field activities

Phase 1 Goal: Demonstrate the proof-of-concept with a prototype



Interactively gain intuitive understanding of CO₂ storage site behavior by:

← Manipulating Inputs

← Exploring Outputs

Deep-learning-based surrogate model for fast forward simulation

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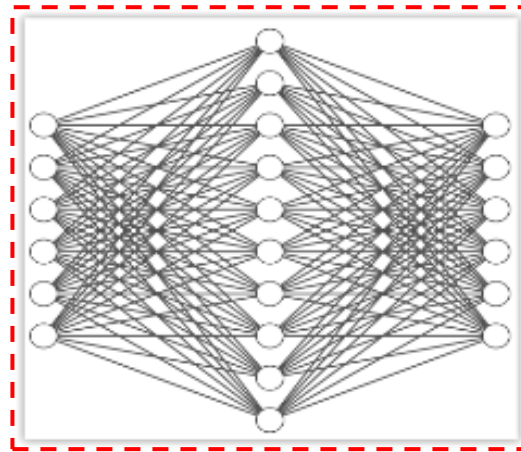
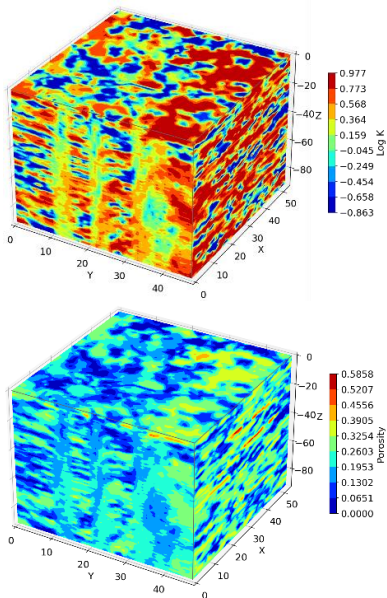
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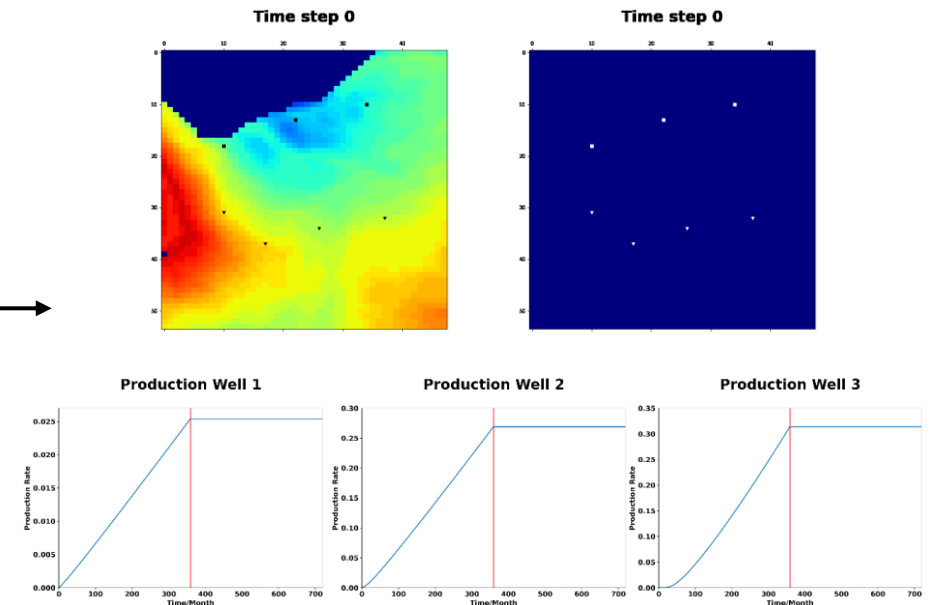
Definitions

- Capture the relationship between the input data and output data and use neural networks as mapping function.
- Faster, more flexible, scalable, and efficient.
- Forward simulation and inverse problem (history matching).

Geological parameter:
Porosity/Permeability



State variables (2D slice for visualization):
Pressure/CO2 saturation/Production rate



Mapping function
(Neural networks)

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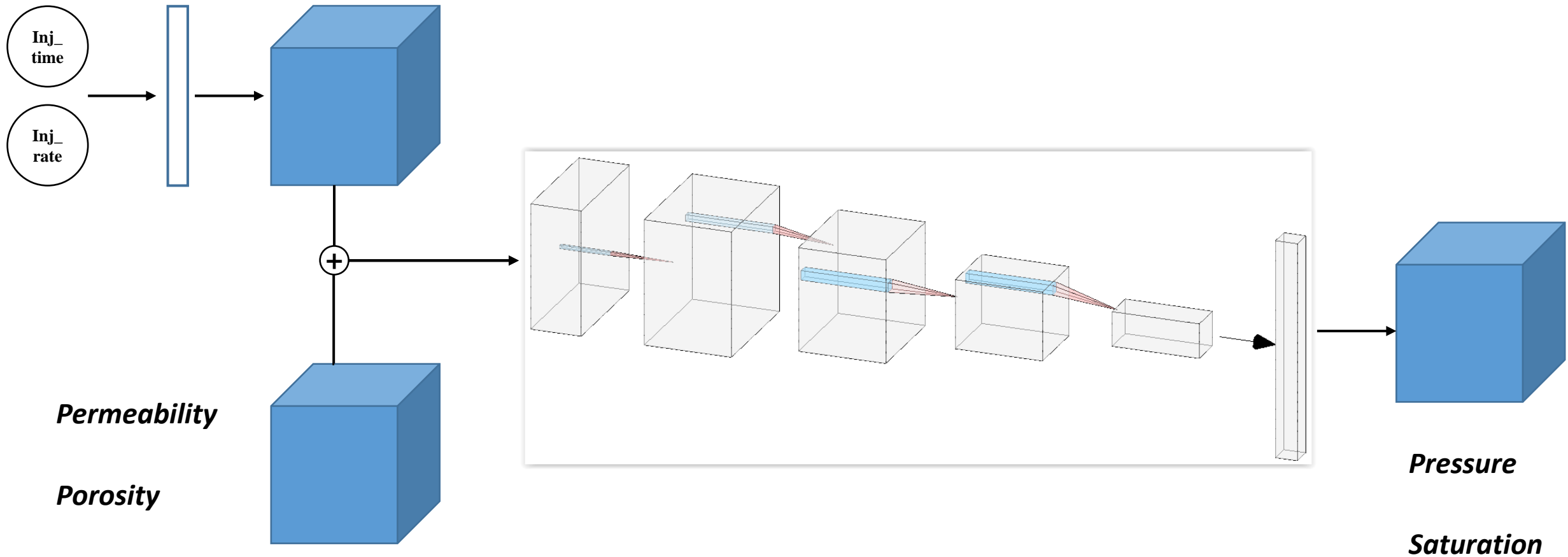
- **1. Convolutional neural network/Multilayer perceptron model**
 - **Dataset: The Illinois Basin – Decatur Project (IBDP) simulations**
 - **Data size: 126, 126, 110**
 - **Time step: 50 (Months)**

- **2. Reduced-order Model**
 - **Dataset: GoM simulations**
 - **Data size: 54, 48, 92**
 - **Time step: 720 (Months)**

CNN/MLP on IBDP

- Model architecture: CNN-MLP
- Input and output overview
- Results: Pressure
- Results: Saturation

Model architecture: CNN-MLP



CNN/MLP on IBDP

- Model architecture: CNN-MLP
- Input and output overview
- Results: Pressure
- Results: Saturation

Input and output overview

- Training, validation, and test split
 - Training (80 realizations): [1, 2, 3, 4, 6, 7, 8, 9, 11,..., 99];
 - Validation (10 realizations): [5, 15, 25, 35, 45, 55, 65, 75, 85, 95];
 - Testing (10 realizations): [10, 20, 30, 40, 50, 60, 70, 80, 90, 100].
- Input data
 - Injection time: (100, 50,);
 - Injection rate: (100, 50,);
 - Permeability: (100, 126, 125, 110, 3);
 - Porosity: (100, 126, 125, 110, 1).
- Output data
 - Pressure: (100, 50, 126, 125, 110, 1);
 - Saturation: (100, 50, 126, 125, 110, 1).

Origin of tartan grid, [1,1,1] on the top surface

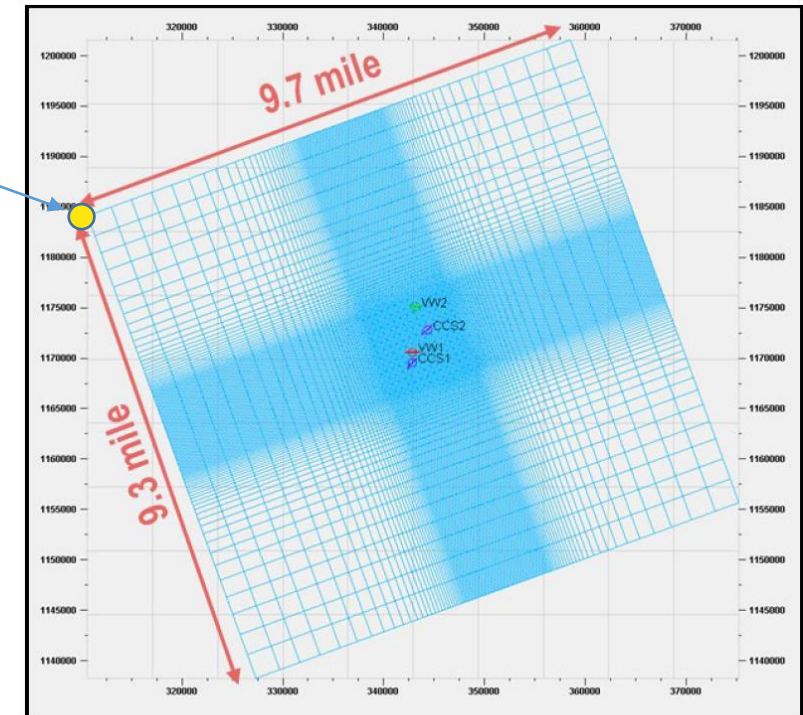
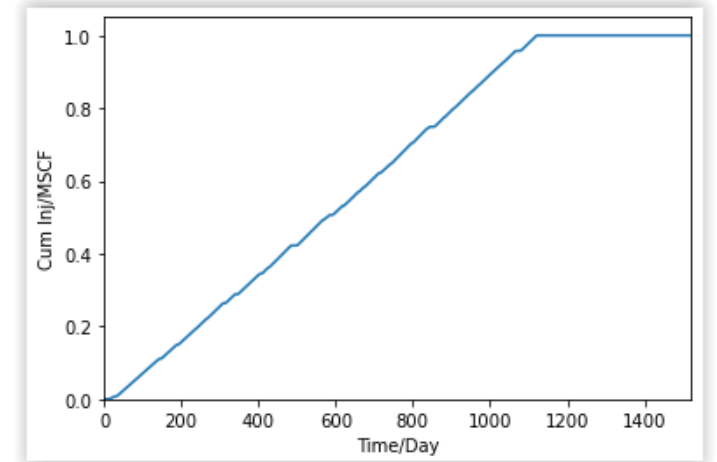
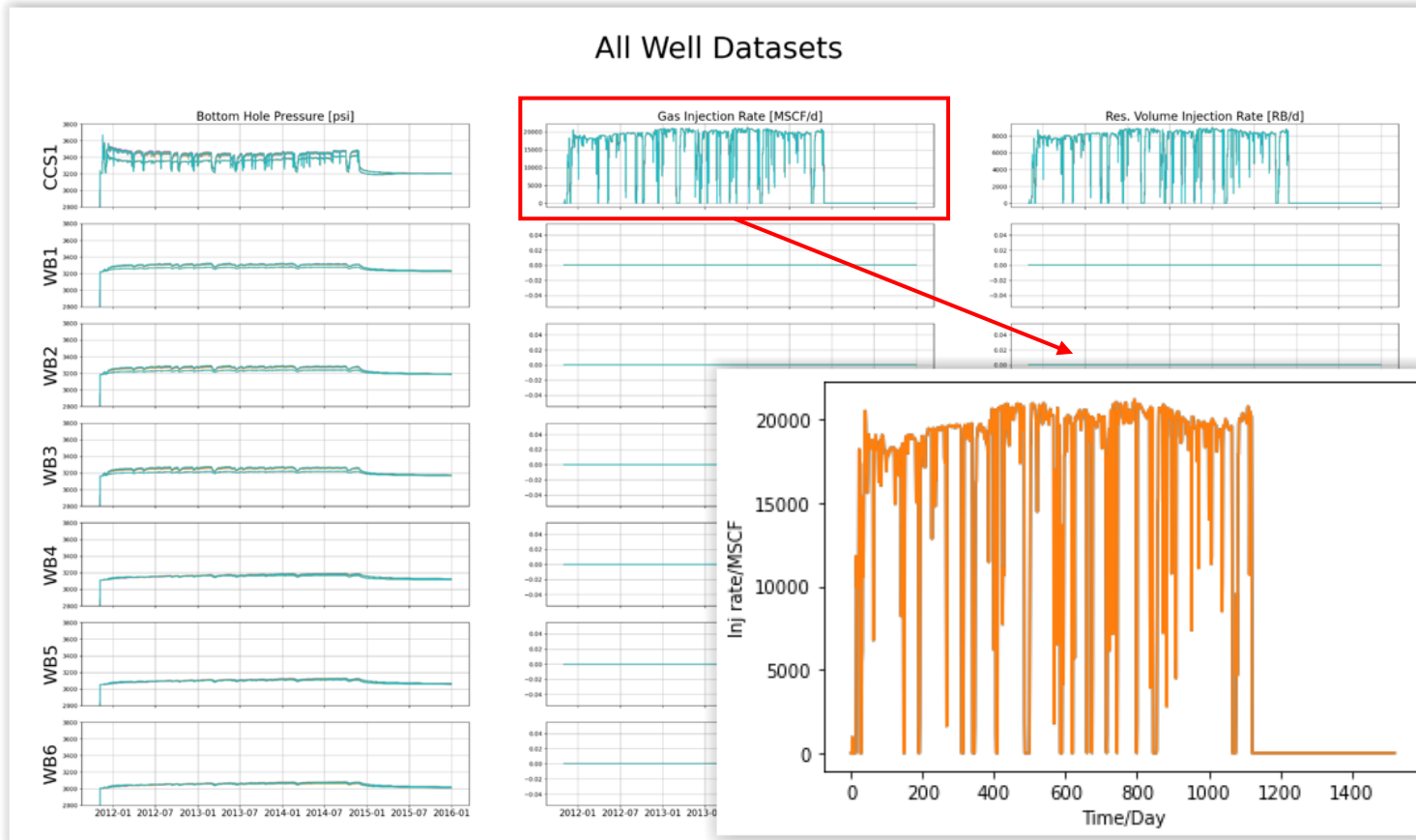


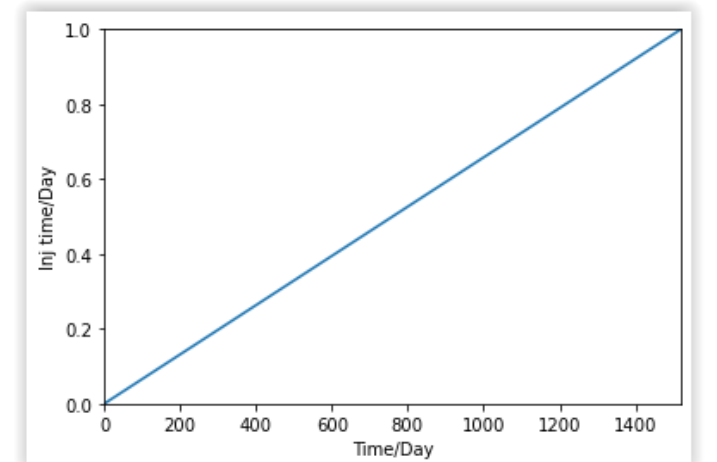
Figure 67. Dynamic model domain and tartan grid.

Pre-processing: Input data

- Injection rate and time



Scaled cumulative injection rate

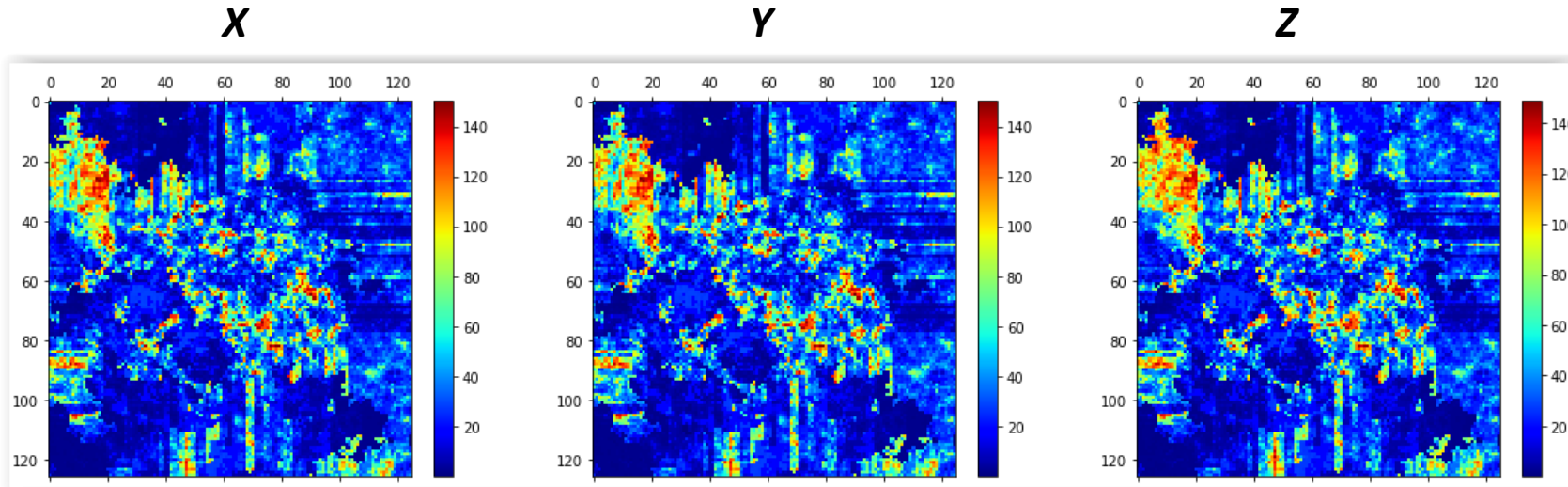


Scaled injection time

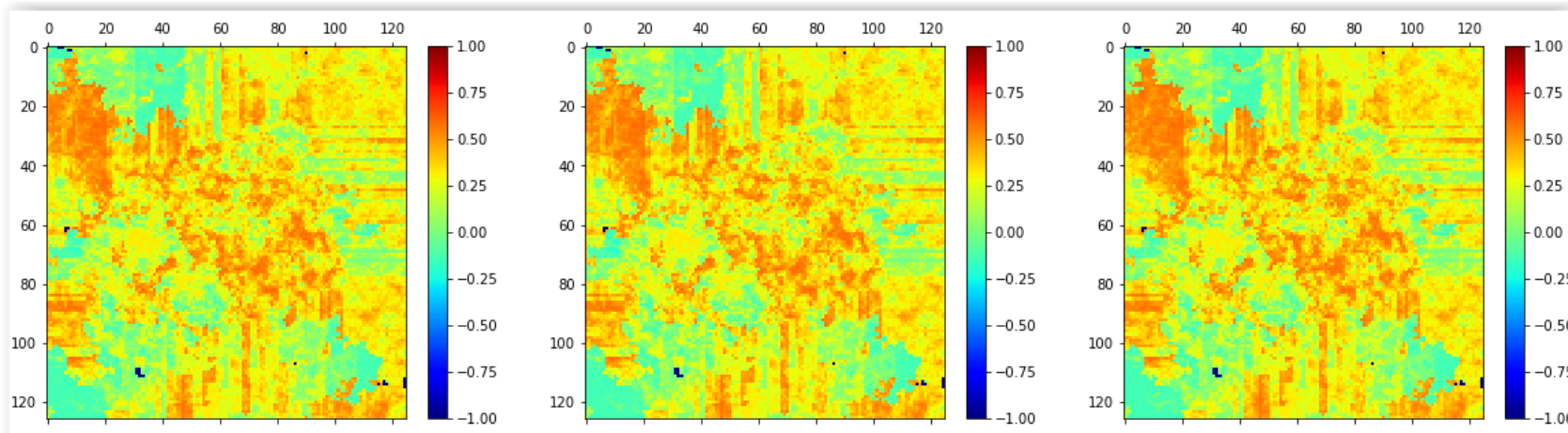
Pre-processing: Input data

- Permeability (X, Y, and Z): scaled logK to [-1, 1];

Original

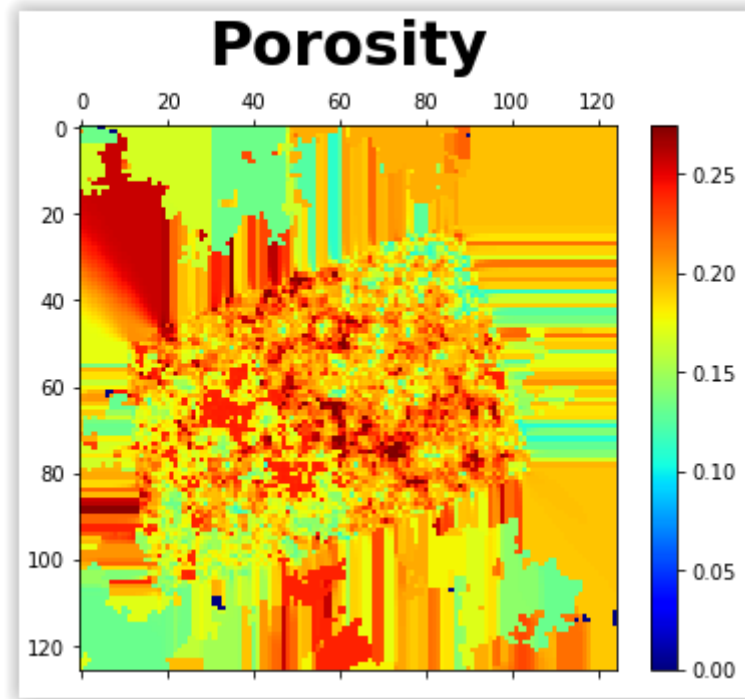


Scaled LogK



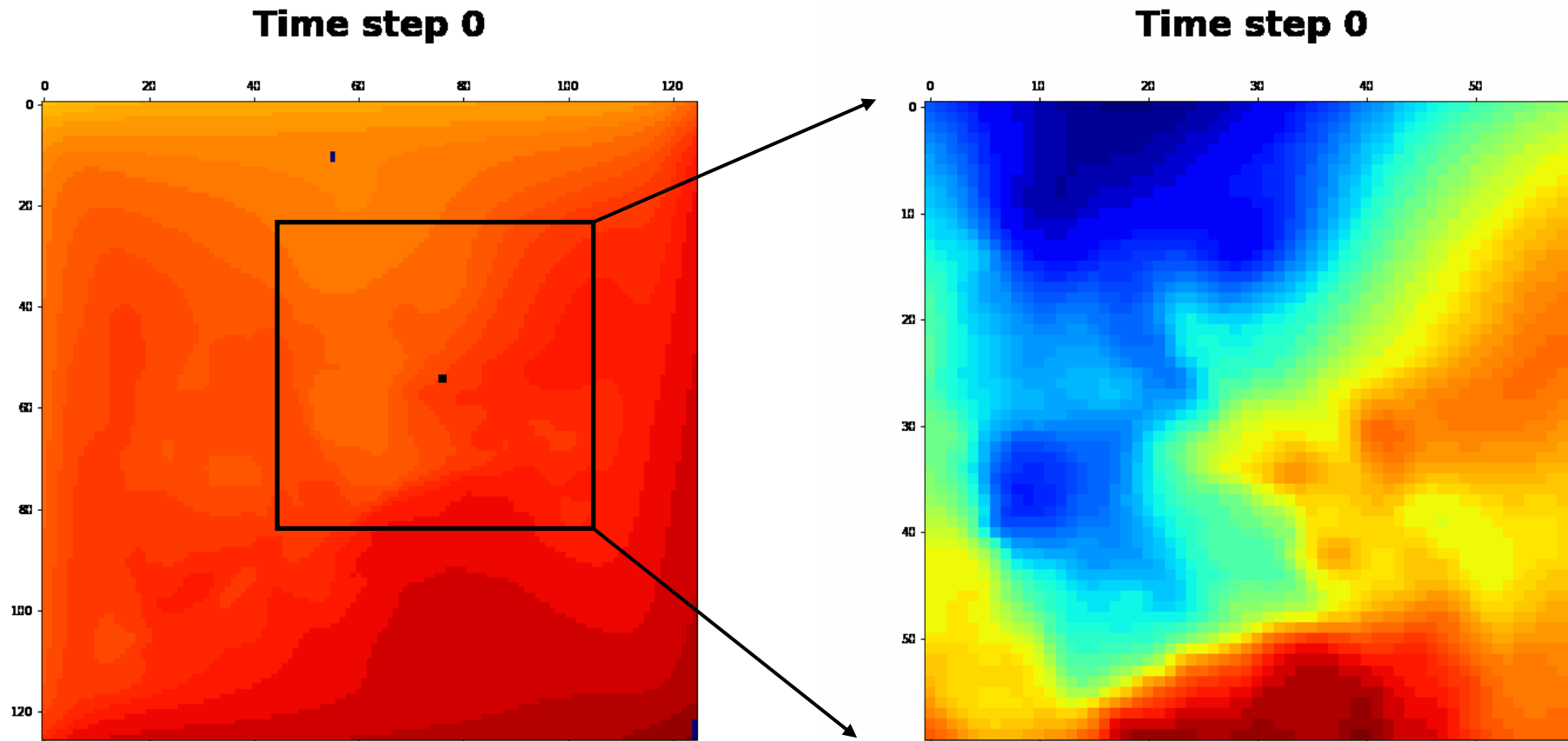
Pre-processing: Input data

- Porosity



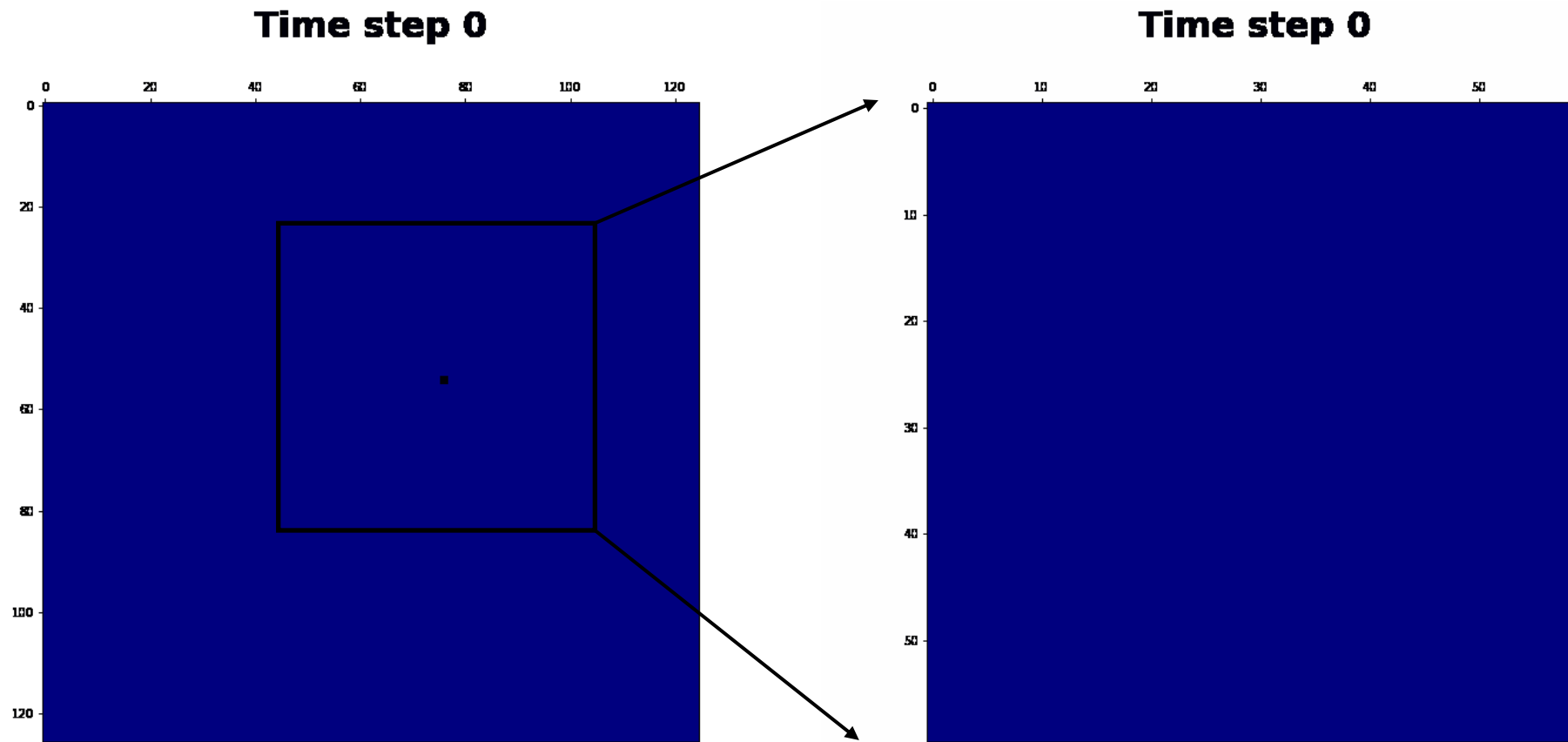
Pre-processing: Output data

- Pressure: Scaled to [0, 1]



Pre-processing: Output data

- Saturation

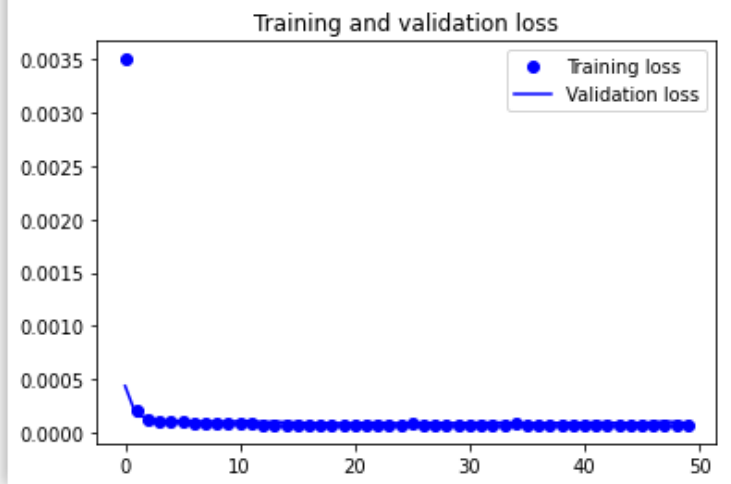
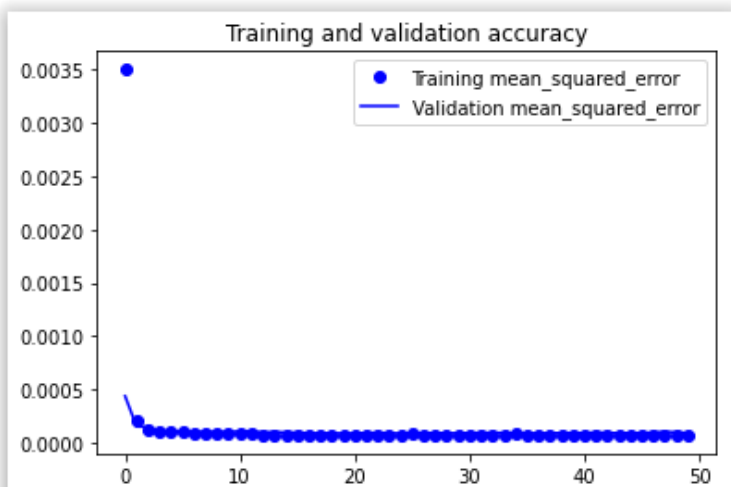


CNN/MLP on IBDP

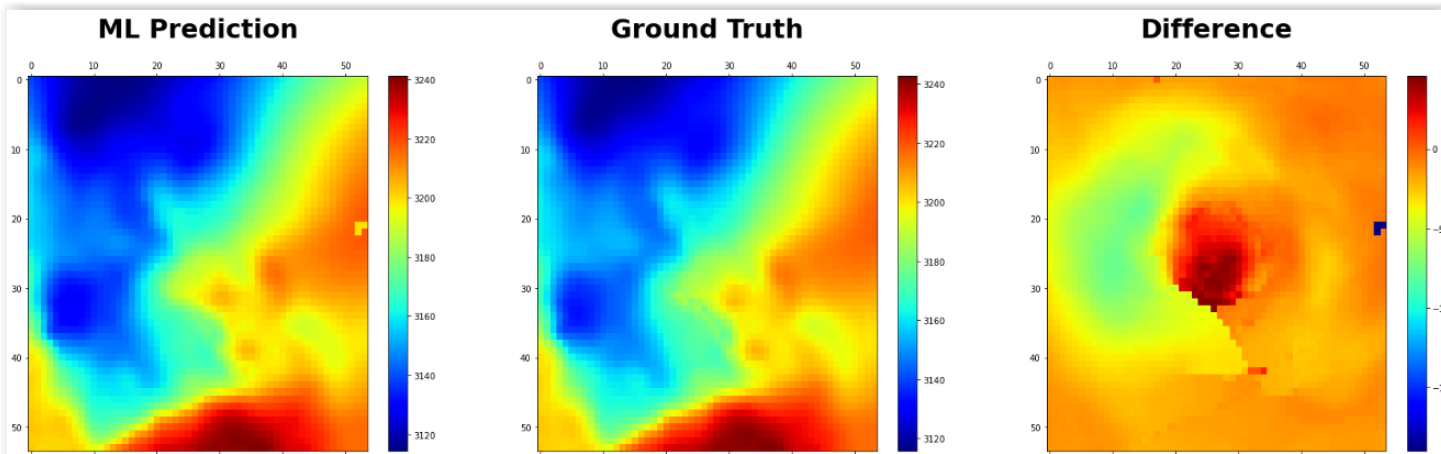
- Model architecture: CNN-MLP
- Input and output overview
- Results: Pressure
- Results: Saturation

Pressure: Good results

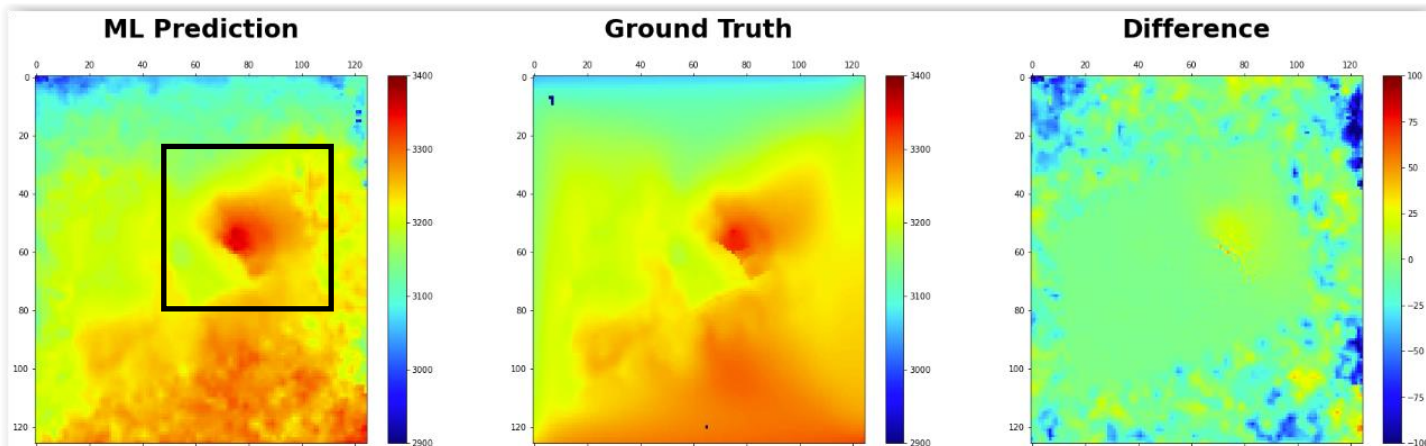
Training curve



Cropped Pressure comparison (mse: 6.2715e-5)

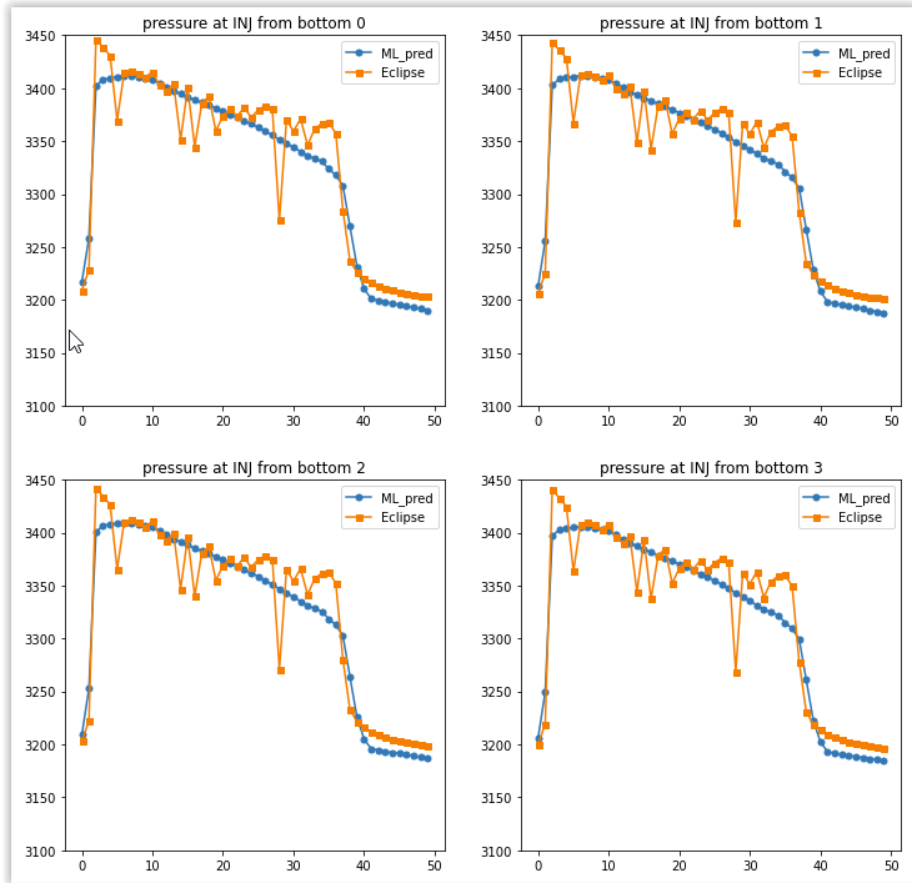


Pressure comparison (mse: 0.001885)

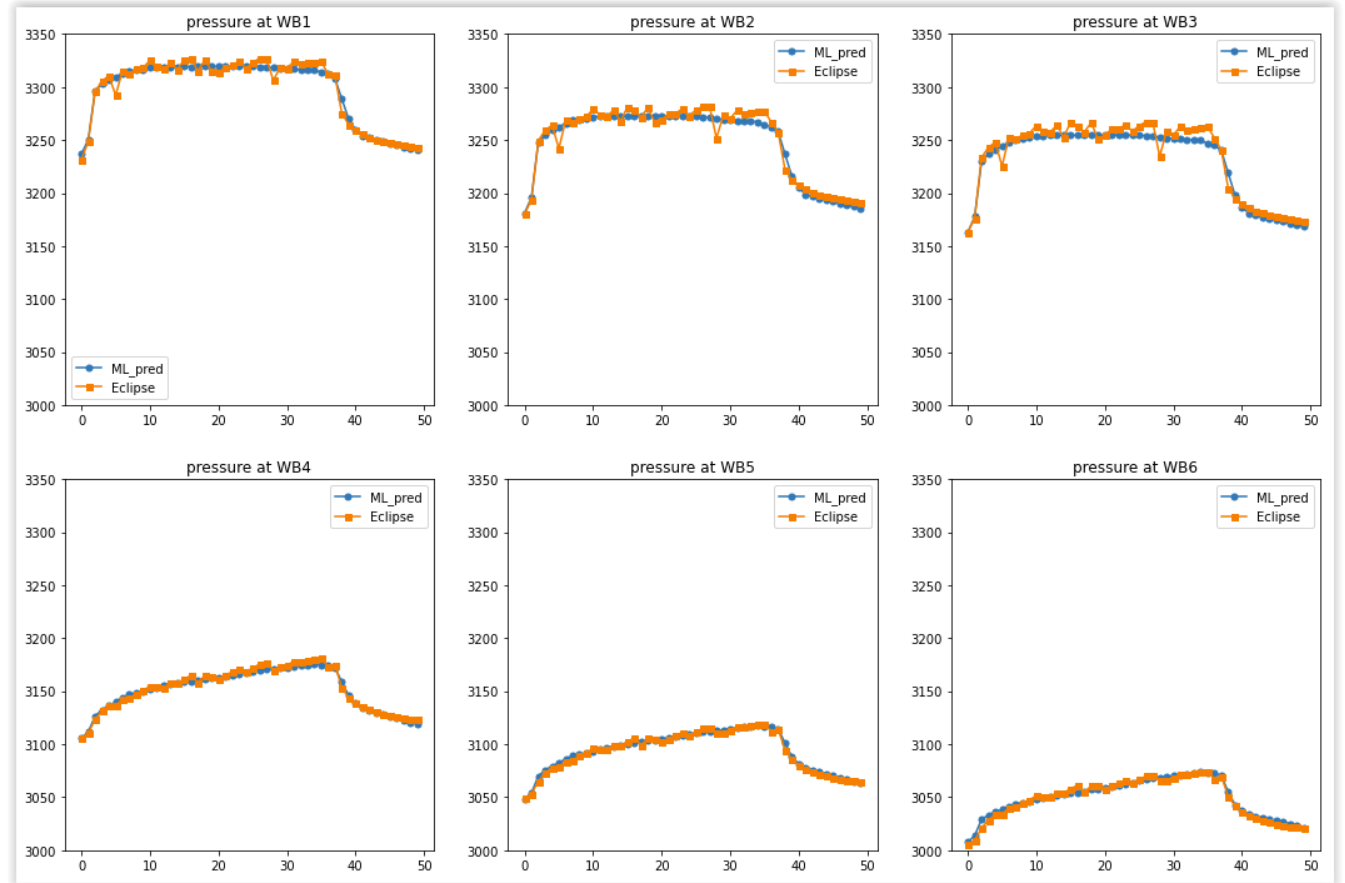


Pressure: injection and monitoring well

Injection well



Monitoring well

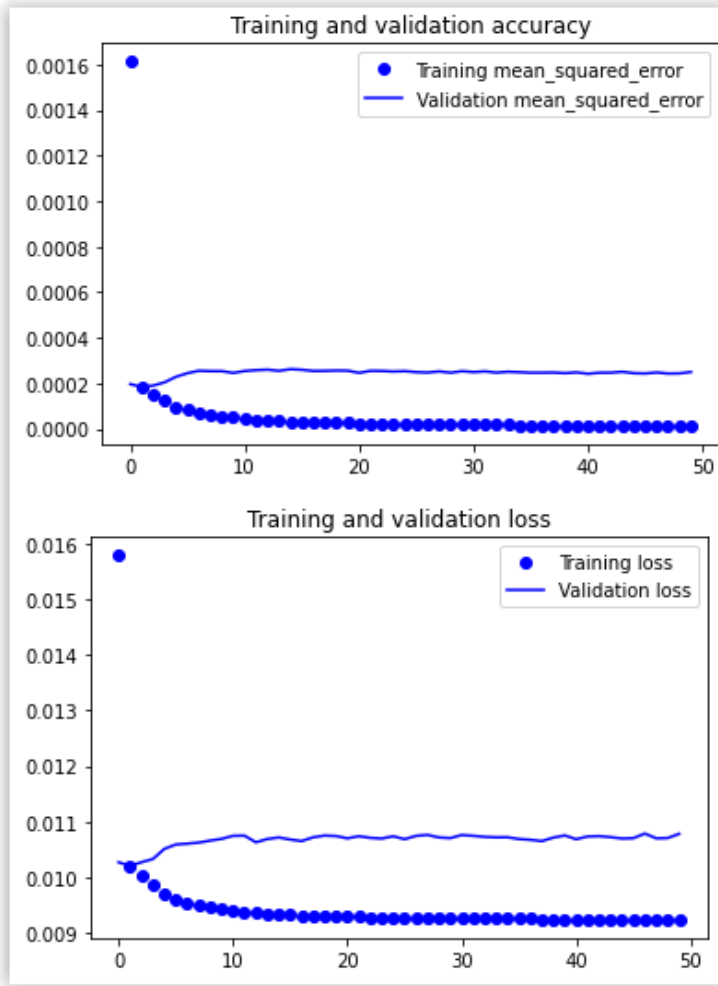


CNN/MLP on IBDP

- Model architecture: CNN-MLP
- Input and output overview
- Results: Pressure
- Results: Saturation

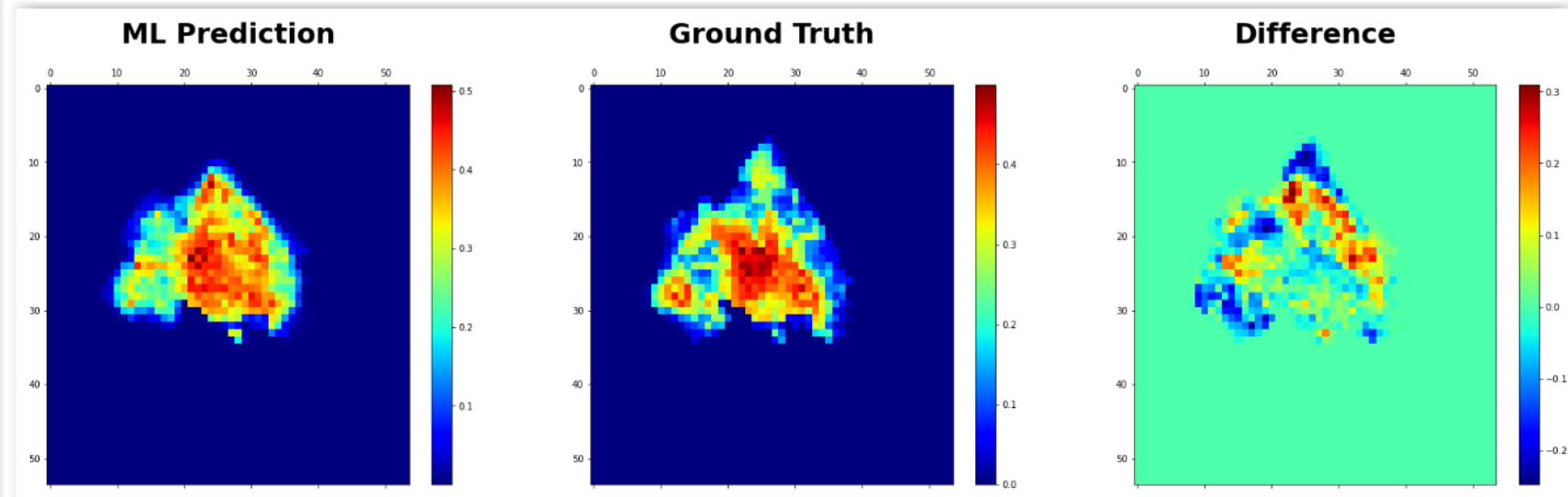
Saturation: Not good

Training curve



Testing (scaled permeability) mse: 0.0001711

Saturation comparison



ROM on GoM

- Problems and motivations
- Dimension reduction and workflow
- Results: Pressure and saturation
- Future work

Problems and motivations

- ML and DL model training:
 - Massive feature numbers: hundreds of thousands or million grid cells;
 - Strong feature correlations;
 - Limited realizations;
 - High computational cost and time for model training.

- Any solutions to improve model performance?

- Can we implement model training with fewer but more representative features?

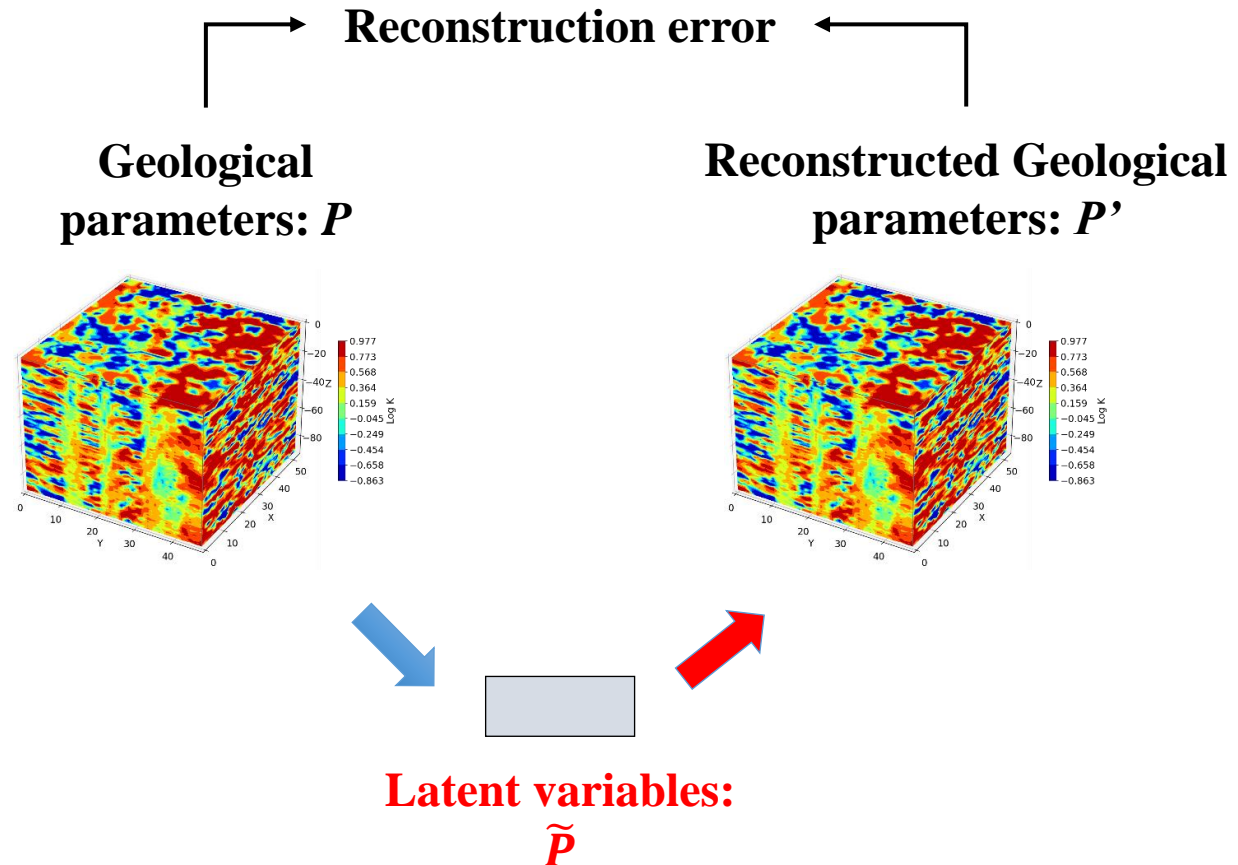


ROM on GoM

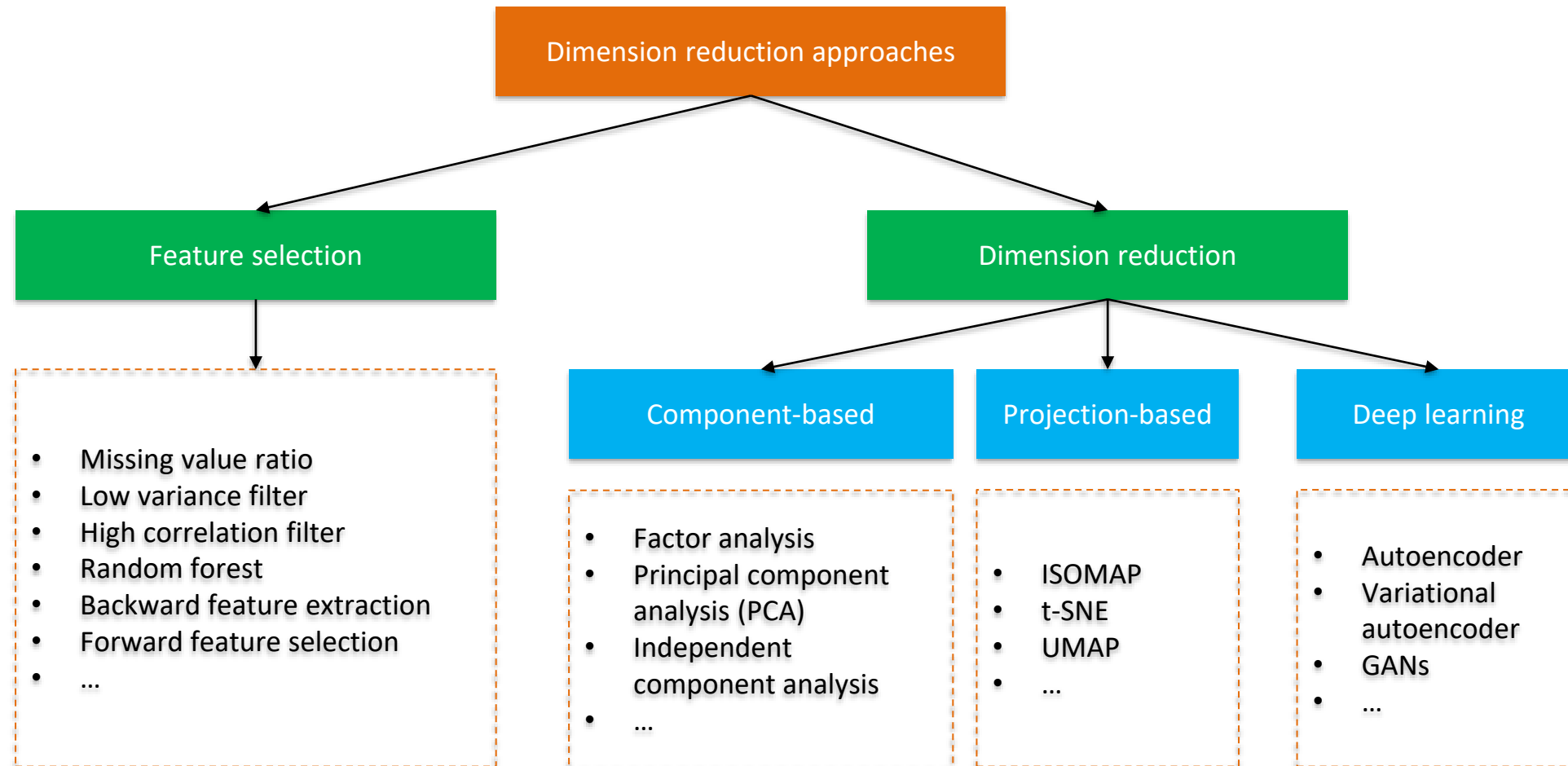
- Problems and motivations
- Dimension reduction and workflow
- Results: Pressure and saturation
- Future work

Dimension reductions

- What can DR do?
 - Reduce feature numbers;
 - Retain important information.

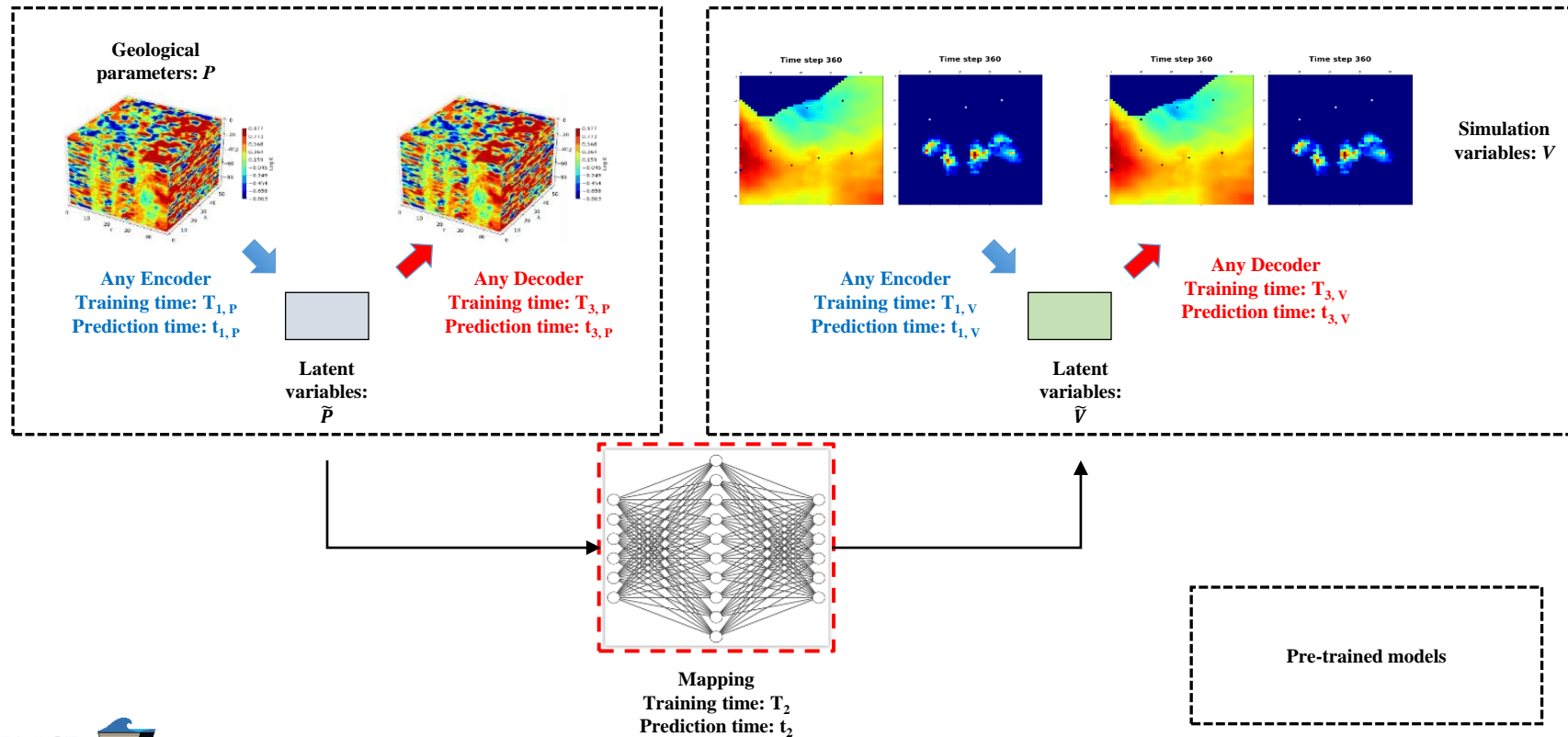


Dimension reductions



Workflow diagram

- Step 1: Dimension reduction models for Geological Parameters and State Variables;
- Step 2: Construct mapping function in latent spaces with less features;
- Step 3: Apply to new realizations or new datasets.



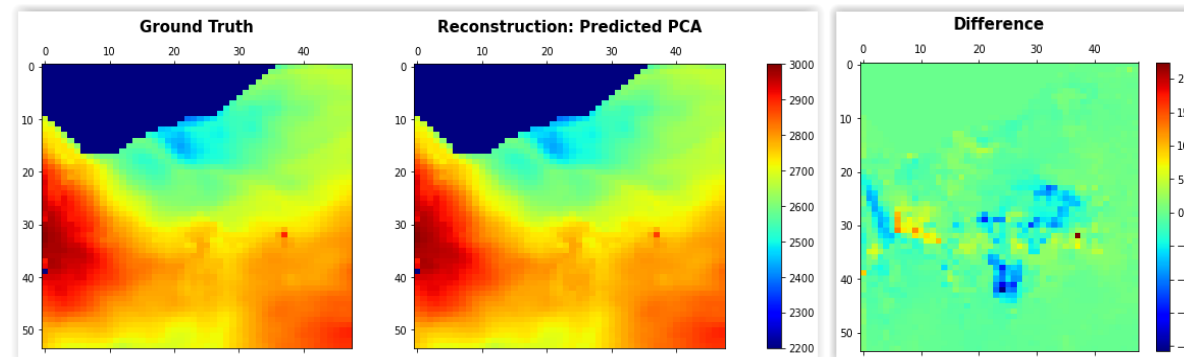
ROM on GoM

- Problems and motivations
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Preliminary results: GoM datasets

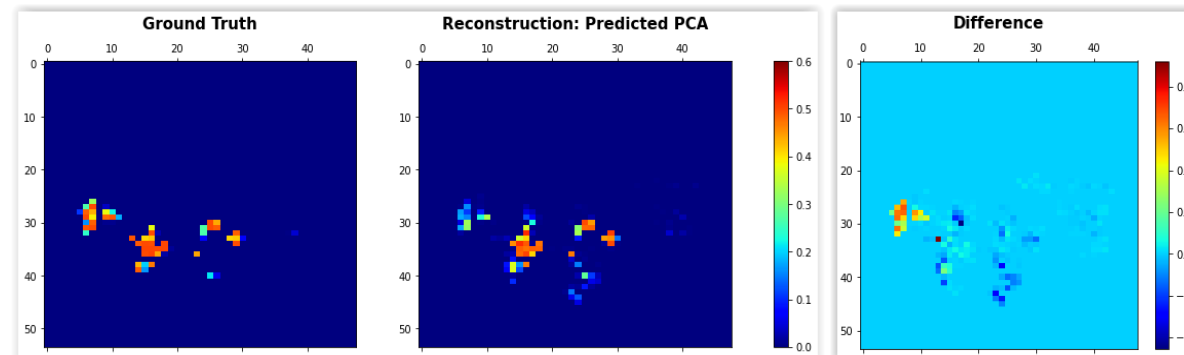
- 3D Pressure: Good with less than 1% errors.

Comparison between Ground Truth and Model Predicted PCA reconstruction



- 3D Saturation: Bad with more than 20% errors.

Comparison between Ground Truth and Model Predicted PCA reconstruction



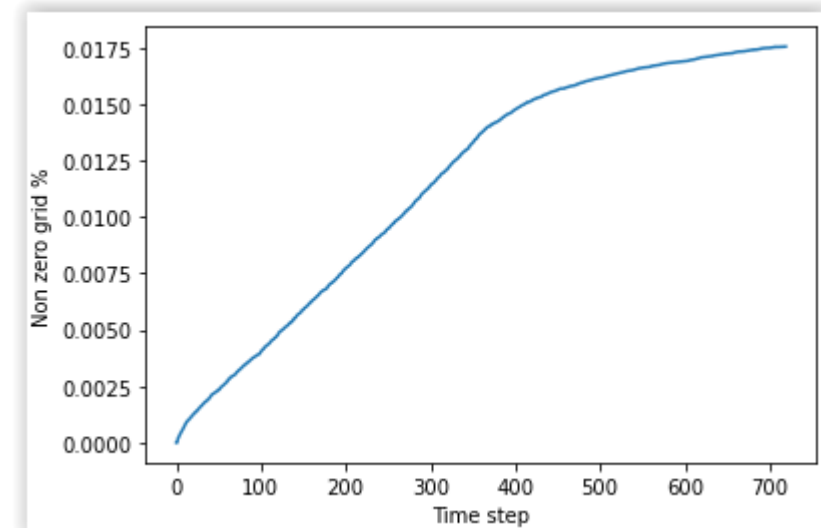
ROM on GoM

- Problems and motivations
- Dimension reduction and workflow
- Results: Pressure and saturation
- Future work

Future works

- **Pressure prediction: from good to better**
 - Improve the accuracy on the large-scale domain
 - Coarsened input data for higher model efficiency
 - ...
- **Saturation prediction: from bad to good**
 - Custom loss function
 - Attention mechanism
 - More powerful models
 - ...

Non-zero saturation grid number fraction versus time



Thank you!